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Hoyle in prep.

Machine Learning for PhotoZ PDFs

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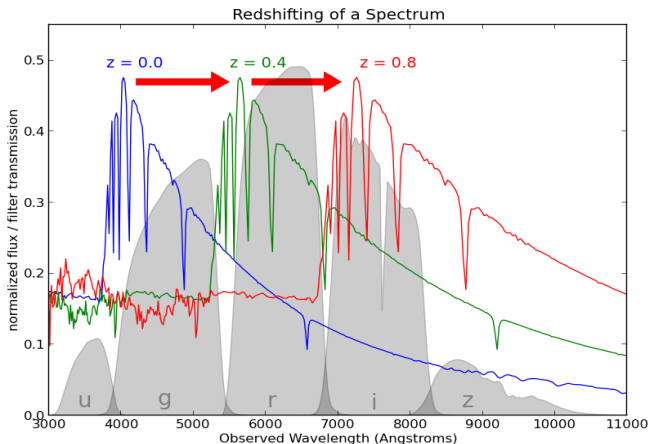
USM Munich

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Outline:

- What are Photometric Redshifts and why do we need them?
- What are Conditional Probability Density Functions (PDFs) and why do we need them?
- How do we know how accurate they are?
- How do we estimate them efficiently?
- How well do our algorithms perform on data?

Photometric Redshifts



Source: http://www.astroml.org/sklearn_tutorial/_images/plot_sdss_filters_2.png

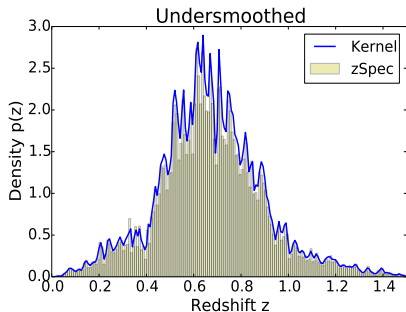
Why Photometric Redshifts?

- Spectroscopic Redshifts expensive (long exposure times especially for faint objects)
- Small datasets
→ insufficient for many cosmological applications (cosmic shear, large scale structure, etc.)
- Solution: Photometric Surveys with spectroscopic overlap

Learn the mapping between the photometry of objects \mathbf{f} and their spectroscopic redshifts z_{spec} and apply this model to objects without spectroscopy. Machine Learning often more accurate than traditional Template Fitting.

(Sánchez et al. 2014 (DES) arXiv:1406.4407)

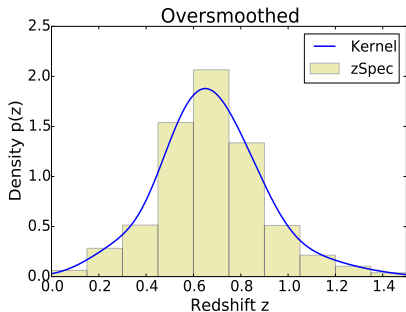
Kernel Density Estimation



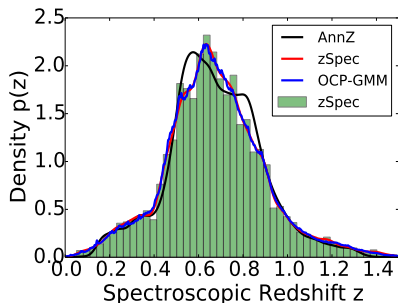
- h : Bandwidth (i.e. standard deviation of Gaussian)
- z_i^{spec} : Kernel center
- h small \rightarrow Undersmoothed
- h big \rightarrow Oversmoothed

Kernel Density Estimate

$$\hat{p}(z) = \frac{1}{N} \sum_{i=1}^N \mathcal{N}(z, z_i^{\text{spec}}, h) \quad (1)$$

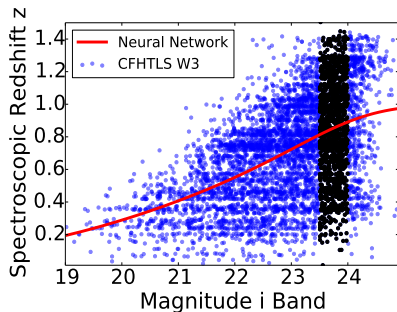


Why PhotoZ PDFs?



- Point Predictions from regression ML algorithms are not able to estimate stacked redshift PDFs
- Unsuit for many applications in cosmology (i.e. Cosmic Shear, Lensing Cluster Mass measurement)

Example in 2D



$$\hat{p}(z|\mathbf{f}) = \sum_{i=1}^N w_i(\mathbf{f}) \mathcal{N}(z, z_i^{\text{spec}}, h) \quad (2)$$

- 2D example with one filter (Data from CFHTLS W3)
- Estimate conditional PDF in black region

The conditional PDF

- The conditional PDF $p(z|\mathbf{f})$ of the objects redshift z given its photometry \mathbf{f} is defined as:

$$p(z|\mathbf{f}) = p(z, \mathbf{f})/p(\mathbf{f}) \quad (3)$$

- Weighted Kernel Density Estimate:

$$\hat{p}(z|\mathbf{f}) = \sum_{i=1}^N w_i(\mathbf{f}) \mathcal{N}(z, \mu = z_i^{\text{spec}}, \sigma = h) \quad (4)$$

- Conditional Mean (Output of ANNz):

$$\hat{z}_{\text{phot}}(\mathbf{f}) = \sum_{i=1}^N w_i(\mathbf{f}) z_i^{\text{spec}} \quad (5)$$

- Conditional Variance:

$$\hat{\sigma}^2(\mathbf{f}) = \sum_{i=1}^N w_i(\mathbf{f}) (z_i^{\text{spec}} - \hat{z}_{\text{phot}}(\mathbf{f}))^2 \quad (6)$$

- Conditional PDF Estimation can be used to obtain arbitrary point predictions (Mean, Mode, Median)
- Incorporate redshift uncertainty in follow up analysis
- Novel algorithm: parametrizes conditional pdf highly efficient (5 numbers/object)
→ Scales well to large datasets (e. g. Euclid, DES)
- Allows the accurate reconstruction of the sample redshift pdf of a photometric sample

$$p(z) = \frac{1}{N} \sum_{i=1}^N p(z|\mathbf{f}_i) \quad (7)$$

Machine Learning Methodology

- Split available data into three datasets (60%, 20%, 20%) training set, validation set, test set
- Estimate the conditional redshift PDF on the training set
- Tune the estimate on the validation set
- Predict the performance on unseen data using the test set

Evaluation Metrics

- Kullback-Leibler Divergence

$$D(p||\hat{p}) = \int_{-\infty}^{\infty} p(\mathbf{x}) \log \left(\frac{p(\mathbf{x})}{\hat{p}(\mathbf{x})} \right) d\mathbf{x} \quad (8)$$

$$D(p||\hat{p}) = \int_{-\infty}^{\infty} p(\mathbf{x}) \log (p(\mathbf{x})) d\mathbf{x} - \int_{-\infty}^{\infty} p(\mathbf{x}) \log (\hat{p}(\mathbf{x})) d\mathbf{x} \quad (9)$$

- **Minimize** $-\int_{-\infty}^{\infty} p(\mathbf{x}) \log (\hat{p}(\mathbf{x}))$
- **Minimize** mean negative log-likelihood loss (MNLL)

$$\text{MNLL} = -\frac{1}{N} \sum_{i=1}^N \log (\hat{p}(z_i|\mathbf{f}_i)) \quad (10)$$

Basic Concept

Remember:

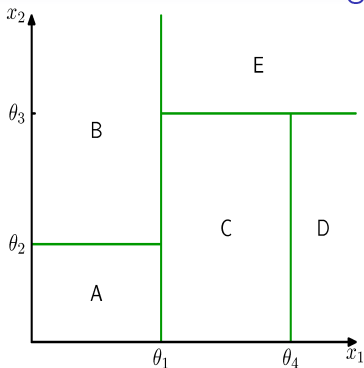
$$\hat{p}(z|\mathbf{f}) = \sum_{i=1}^{N_{\text{tr}}} w(\mathbf{f}_i) \mathcal{N}(z, \mu = z_i^{\text{spec}}, \sigma = h) \quad (11)$$

N_{tr} : Number of objects in the **training set**

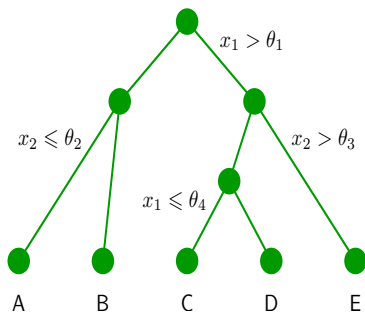
Questions:

- How to estimate the weights $w_i(\mathbf{f})$?
 - Using a Quantile Regression Forest
 - Using an Ordinal Classification Approach
- Given $\{w_i(\mathbf{f}), z_i^{\text{spec}}\}$ how do we estimate the objects PDF?
 - Weighted Kernel Density Estimate (Eqn. 11)
 - Linear combination of normal densities (Gaussian Mixture Model)

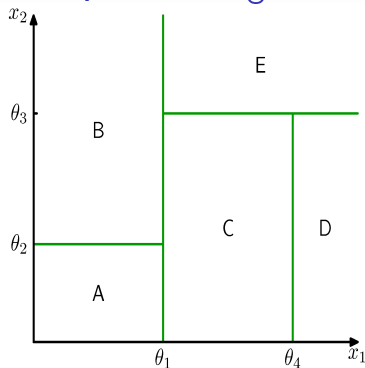
Regression Tree



research.microsoft.com/en-us/um/people/cmbishop/prml/index.htm



Quantile Regression Forest (Meinshausen 2006)



Single Tree:

$$w_i(\mathbf{f}) = \frac{I(\mathbf{f}_i^{\text{tr}} \in \mathcal{R}_{I(\mathbf{f}, \theta)})}{\sum_{j=1}^{N_{\text{tr}}} I(\mathbf{f}_j^{\text{tr}} \in \mathcal{R}_{I(\mathbf{f}, \theta)})} \quad (12)$$

Tree Ensemble:

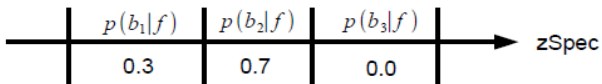
$$w_i(\mathbf{f}) = \frac{1}{k} \sum_{b=1}^k w_i(\mathbf{f}, \theta_b) \quad (13)$$

θ : parametrizes how the tree was grown

The Highest Weight Element

- Useful "by-product" from Quantile Regression Forest
 - Use weights from Quantile Regression Forest
 - Select the spectroscopic redshift with the highest weight
 - z_i^{spec} for $\max(w_i(\mathbf{f}))$
 - Similar to Nearest Neighbour estimator
 - Single floating point number per object
- Very efficient estimator for sample redshift PDF

Classification for PhotoZ PDFs



How do we estimate the weights $w_i(\mathbf{f})$?

- Idea: Bin the redshift range and use a probabilistic classifier to reconstruct the PDF. (Schapire et al. 2002, Frank et al. 2009)

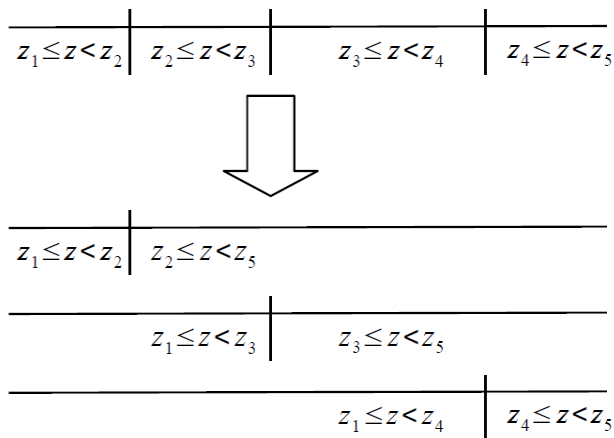
$$w_i(\mathbf{f}) = \frac{\hat{p}(b_i|\mathbf{f})}{n_{b_i}} \quad (14)$$

- b_i : Index denoting the bin
- $\hat{p}(b_i|\mathbf{f})$: probability that the redshift of an object with photometry \mathbf{f} falls into bin b_i .
- n_{b_i} : number of training set objects in bin b_i

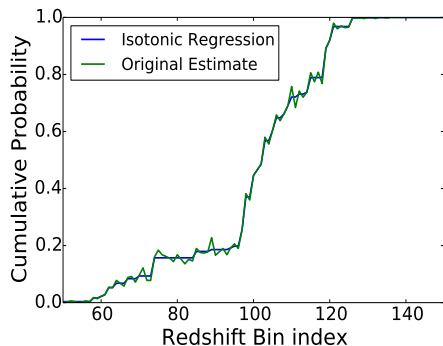
Ordinal Classification

- Idea: Treat the binned redshift as an ordinal scale variable to improve classification. (Frank et al. 2001)
- Nominal Classes:
 $p(\text{Temp} = \text{Cool}|\mathbf{x})$, $p(\text{Temp} = \text{Mild}|\mathbf{x})$, $p(\text{Temp} = \text{Hot}|\mathbf{x})$
- Ordinal Classes:
 $p(\text{Temp} > \text{Cool}|\mathbf{x})$, $p(\text{Temp} > \text{Mild}|\mathbf{x})$
- Recover Class probabilities:
 $p(\text{Temp} = \text{Cool}|\mathbf{x}) = 1 - p(\text{Temp} > \text{Cool}|\mathbf{x})$,
 $p(\text{Temp} = \text{Hot}|\mathbf{x}) = p(\text{Temp} > \text{Mild}|\mathbf{x})$,
 $p(\text{Temp} = \text{Mild}|\mathbf{x}) = p(\text{Temp} > \text{Cool}|\mathbf{x}) - p(\text{Temp} > \text{Mild}|\mathbf{x})$

Application to binned redshift



Calibrating Class Probabilities



- Errors in classification
- Monotonicity of cumulative probability not guaranteed
- Calibrate using Isotonic (Monotonic) Regression

Recapitulation

- The photometric redshift PDF for a new object is estimated from the **training set**

$$\{w_i(\mathbf{f}), z_i^{\text{spec}}\} \quad (15)$$

- The weights $\{w_i(\mathbf{f})\}$ are estimated using:
 - Quantile Regression Forest (QRF)
 - Not Ordinal (nominal) Classification PDF estimate (NOCP)
 - Ordinal Classification PDF estimate (OCP)
- The Highest Weight Element (HWE) is a single floating point estimate for the stacked redshift PDF
- **Find density estimate for the weighted spectroscopic redshifts in the training set**

Density Estimation

- Kernel Density Estimation

$$\hat{p}(z|\mathbf{f}) = \sum_{i=1}^{N_{\text{tr}}} w_i(\mathbf{f}) \mathcal{N}(z, \mu = z_i^{\text{spec}}, \sigma = h) \quad (16)$$

- Select bandwidth h
- Density Estimation using Gaussian Mixture Models

$$\hat{p}(z|\mathbf{f}) = \sum_{i=1}^K \alpha_i(\mathbf{f}) \mathcal{N}(z, \mu_i(\mathbf{f}), \sigma_i(\mathbf{f})) \quad (17)$$

- Select number of mixture components K
- Fit mixture components to weighted data

Bandwidth Selection

- 'Scott' Bandwidth:

$$\hat{\sigma}_{\text{Scott}} = a \frac{\hat{\sigma}}{N_{\text{tr}}^{1/5}} \quad (18)$$

- 'Hjort' Bandwidth:

$$\hat{\sigma}_{\text{Hjort}} = a \frac{\hat{\sigma}}{N_{\text{tr}}^{1/4}} \quad (19)$$

- Standard Deviation

$$\hat{\sigma}^2(\mathbf{f}) = \sum_{i=1}^{N_{\text{tr}}} w_i(\mathbf{f}) (z_i^{\text{spec}} - \hat{z}_{\text{phot}}(\mathbf{f}))^2 \quad (20)$$

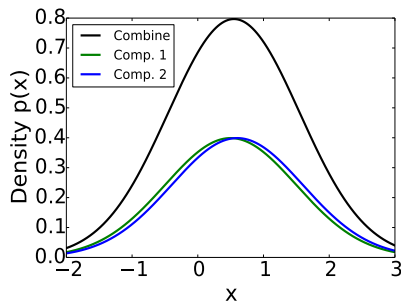
- Select the factor a using the validation set

Gaussian Mixture Model

Motivation: Sparse parametrization

- More efficient (i.e. 5 floating point numbers per object)
- Easier to interpret
- Fit the parameters $\alpha_i(\mathbf{f})$, $\mu_i(\mathbf{f})$ and $\sigma_i(\mathbf{f})$ to the weighted data $\{w_i(\mathbf{f}), z_i^{\text{spec}}\}$
- Fix a maximum number of mixture components K_{max} using the validation set
- Select the number of components $0 < K \leq K_{\text{max}}$ on a per-object basis that minimizes the normalized entropy criterion

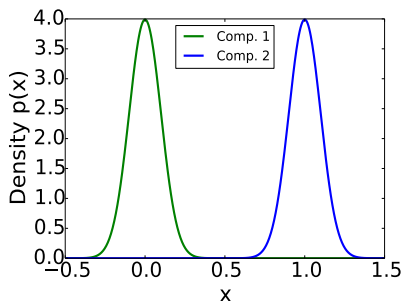
Normalized Entropy Criterion (Celeux & Soromenho 1996)



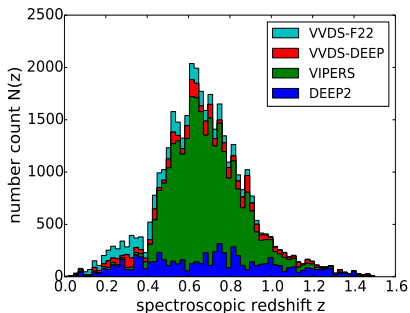
- $E(K)$: Entropy measures "overlap" between components
- $L(K)$: maximum weighted log-likelihood for the model
- $L(K)$ (increasing in K) balanced by $E(K)$ (favours less overlap between components)

Minimize

$$NEC(K) = \frac{E(K)}{L(K) - L(1)} \quad (21)$$

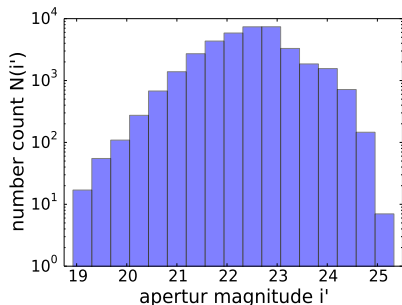


Dataset

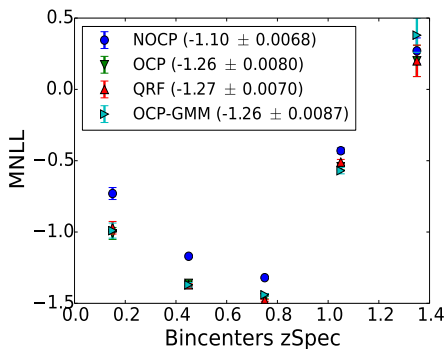


- 31183 objects with $i' \leq 22.5$
- 6561 objects with $22.5 < i' \leq 24.5$

- Subsample from CFHTLS Wide (Brimouille et. al. 2013)
- 5 band photometry (u^*, g', r', i', z')



Redshift Conditional PDF

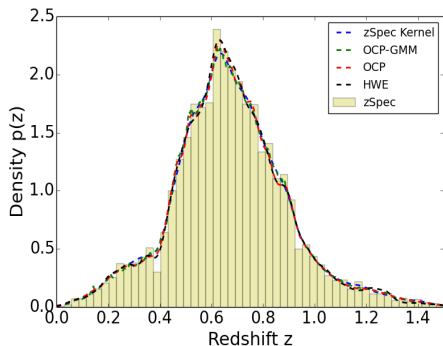


- **Minimize** mean negative log-likelihood loss (MNLL)

$$\text{MNLL} = -\frac{1}{N} \sum_{i=1}^N \log(\hat{p}(z_i | \mathbf{f}_i)) \quad (22)$$

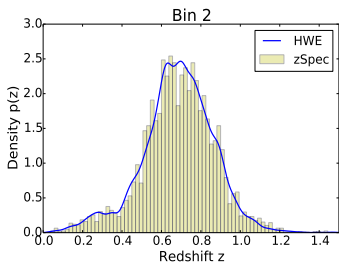
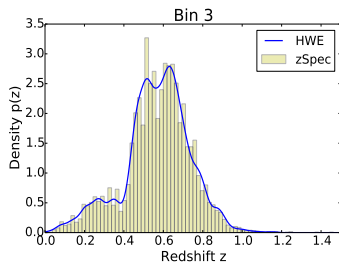
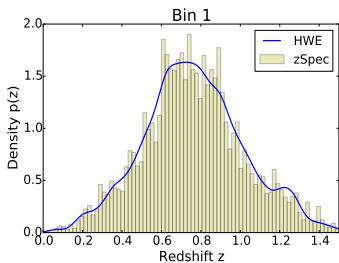
- Ordinal Classification improves performance
- Gaussian Mixture density estimate competitive with kernel and **more efficient**
→ 5 floating point numbers per object

Stacked Redshift PDF



- Highest Weight Element accurate estimator of the redshift sample PDF
- z_i^{spec} associated with $\max(w_i(\mathbf{f}))$
- **Efficient:** 1 floating point number per object

Magnitude Selected Samples



- Selected on scaled i' band flux by equal frequency binning

$$f_{\text{scaled},i'} = \frac{f_{i'} - \mu_{i'}}{\sigma_{i'}} \quad (23)$$

- $\mu_{i'}$: average flux
- $\sigma_{i'}$: standard deviation of all fluxes (NOT flux error)

Conclusions

- Highest Weight Element accurately estimates the redshift sample PDF (1 floating point number)
- Ordinal classification improves classification accuracy
- Gaussian Mixtures very efficient (5 floating point numbers) for PDF estimation
- Point predictions (i.e. conditional mean) don't provide enough information for many applications in cosmology
→ Currently actively explored by us