

Bayesian methods in the search for gravitational waves

Reinhard Prix

Albert-Einstein-Institut Hannover

Bayes forum

Garching, Oct 7 2016

Probability Theory: extends deductive logic to situations of *incomplete information* (☞ “Inference”) [Jaynes, Cox]

Logical propositions, e.g.

A = “There is a signal in this data”

$A(h_0, f)$ = “The signal has amplitude h_0 and frequency f ”

$P(A|I)$ \equiv quantifies plausibility of A being true *given* I
 I = relevant background knowledge and assumptions

- ☞ quantifies an **observer's** state of knowledge about A
- ☞ **not** a property of the observed system! (“Mind projection fallacy”)

(Cox 1946, 1961, Jaynes) Requiring 3 conditions for $P(A|I)$:

(i) $P \in \mathbb{R}$, (ii) consistency, (iii) agreement with “common sense”
one can *derive* **unique** laws of probability (up to gauge):

The Three Laws

$$\textcircled{1} P(A|I) \in [0, 1] \quad \begin{cases} P(A|I) = 1 & \Leftrightarrow (A|I) \text{ certainly true} \\ P(A|I) = 0 & \Leftrightarrow (A|I) \text{ certainly false} \end{cases}$$

$$\textcircled{2} P(A|I) + P(\text{not } A|I) = 1$$

$$\textcircled{3} P(A \text{ and } B|I) = P(A|B, I) P(B|I)$$

👉 Bayes' theorem: $P(A|B, I) = P(B|A, I) \frac{P(A|I)}{P(B|I)}$

👉 Sum rule: $P(A \text{ or } B|I) = P(A|I) + P(B|I) - P(A \text{ and } B|I)$

Bayesian data analysis

Q: We observe data \mathbf{x} , what can we learn from it?

Formulate “question” as a proposition A and *compute* $P(A|\mathbf{x}, I)$

The ‘standard’ GW hypotheses

\mathcal{H}_G : data is pure Gaussian noise: $\mathbf{x}(t) = \mathbf{n}(t)$

\mathcal{H}_S : data is *signal* + Gaussian noise: $\mathbf{x}(t) = \mathbf{n}(t) + \mathbf{h}(t; \theta)$

- signal parameters, e.g. $\theta = \{ \text{masses, spins, position} \dots \}$
- Data from several detectors: $\mathbf{x} = \{ \mathbf{x}^{\text{H1}}, \mathbf{x}^{\text{L1}}, \dots \}$
- Gaussian noise pdf: $P(\mathbf{n}|\mathcal{H}_G) = \kappa e^{-\frac{1}{2}(\mathbf{n}|\mathbf{n})}$
 - 👉 “matched-filter” scalar product $(x|y) = \int \frac{\tilde{x}(f)\tilde{y}^*(f)}{S_n(f)} df$
 - 👉 *assumes known* (i.e. estimated) noise PSDs $S_n(f)$
(alternative: marginalize)

Q1: Given data \mathbf{x} , what can we learn about \mathcal{H}_G and \mathcal{H}_S ?

Two possibilities:

- 1 Complete set of hypotheses: directly compute $P(\mathcal{H}_S|\mathbf{x}, I)$
- 2 Alternative: relative probabilities (“odds”):

$$O_{S/G}(\mathbf{x}) \equiv \frac{P(\mathcal{H}_S|\mathbf{x})}{P(\mathcal{H}_G|\mathbf{x})} = \underbrace{\frac{P(\mathbf{x}|\mathcal{H}_S)}{P(\mathbf{x}|\mathcal{H}_G)}}_{\text{Bayes factor } B_{S/G}} \times \underbrace{\frac{P(\mathcal{H}_S)}{P(\mathcal{H}_G)}}_{\text{prior odds}},$$

 $B_{S/G}(\mathbf{x})$ “updates” our knowledge about $\mathcal{H}_S/\mathcal{H}_G$

Q1': How to deal with unknown signal parameters θ ?

Likelihood ratio (function):

$$\begin{aligned}\mathcal{L}(\mathbf{x}; \theta) &\equiv \frac{P(\mathbf{x}|\mathcal{H}_S, \theta)}{P(\mathbf{x}|\mathcal{H}_G)} \\ &= \exp \left[(\mathbf{x}|\mathbf{h}(\theta)) - \frac{1}{2} (\mathbf{h}(\theta)|\mathbf{h}(\theta)) \right]\end{aligned}$$

Laws of probability  “marginalize”:

$$B_{S/G}(\mathbf{x}) = \int \mathcal{L}(\mathbf{x}; \theta) P(\theta|\mathcal{H}_S) d\theta$$

“Orthodox” maximum-likelihood (ML) approach:

$$\mathcal{L}_{\text{ML}}(\mathbf{x}) = \max_{\theta} \mathcal{L}(\mathbf{x}; \theta)$$

Bayesian parameter estimation

Q2: What can we learn about signal parameters θ ?

☞ directly compute posterior probability $P(\theta|\mathbf{x}, \mathcal{H}_S)$

$$\underbrace{P(\theta|\mathbf{x}, \mathcal{H}_S)}_{\text{posterior}} \propto \underbrace{\mathcal{L}(\mathbf{x}; \theta)}_{\text{likelihood function}} \times \underbrace{P(\theta|\mathcal{H}_S)}_{\text{prior}}$$

Q2': What can we learn about a *subset* of parameters λ ?

$\theta = \{\mathcal{A}, \lambda\}$ ☞ “marginalize” over “uninteresting” parameters \mathcal{A} :

$$P(\lambda|\mathcal{H}_S, \mathbf{x}) = \int P(\mathcal{A}, \lambda|\mathcal{H}_S) d\mathcal{A} \propto \int \mathcal{L}(\mathbf{x}; \theta) P(\theta|\mathcal{H}_S) d\mathcal{A}$$

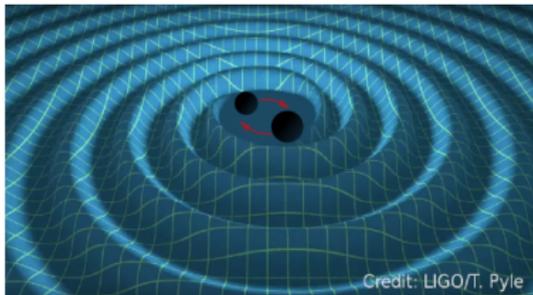
Summary: Bayesian data analysis – strengths and weaknesses

Bayesian probability is the “perfect *machine*” for data analysis, but the difficulty lies in

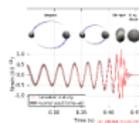
- choosing the “right” inputs:
hypotheses \mathcal{H}_i , priors $P(\theta|\mathcal{H})$, ...
 - ☞ What do we (really) know?
 - ☞ How to quantify/formalize it?
- evaluation: can write down “optimal answer”, but may be
 - impossible to compute
 - much slower than an efficient “ad-hoc” statistic
 - not more detection power than empirical/ad-hoc approaches

☞ use wisely ...

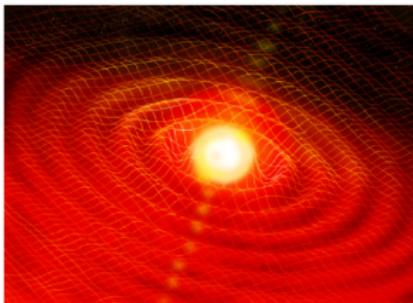
Compact Binary Coalescence (CBC)



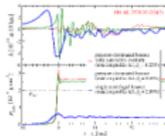
- sources: inspirals of compact objects (NSs, BHs)
- strong ($h_0 \sim 10^{-21}$) & short $\sim \mathcal{O}(s)$
- approximate waveforms from GR



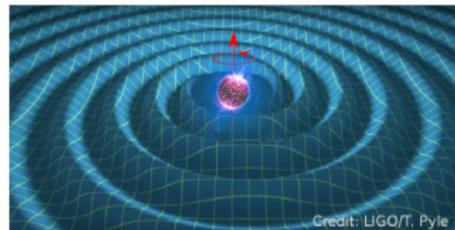
'Unmodelled' bursts



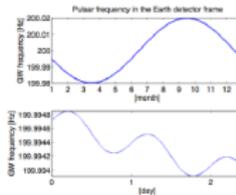
- sources: all CBC sources + supernovae, GRBs, ...
- strong ($h_0 \sim \mathcal{O}(10^{-21})$)
- short $\sim \mathcal{O}(s)$
- minimal assumptions on waveform



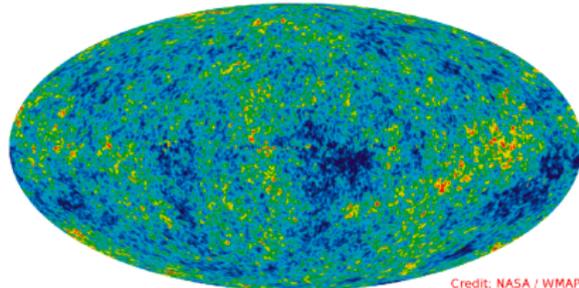
Continuous Waves (CW)



- sources: rotating, non-axisymmetric neutron stars
- weak ($h_0 \lesssim 10^{-25}$)
- long-lasting (days – years): integrate to gain $\text{SNR} \propto \sqrt{T}$
- quasi-periodic, sinusoidal waveform
- signal **phase-** and **amplitude-** modulated
- parameter-space resolution (number of templates) grows $\mathcal{N} \propto T^n$ with $n \gtrsim 5$
- sensitivity limited by finite computational power
- semi-coherent methods...

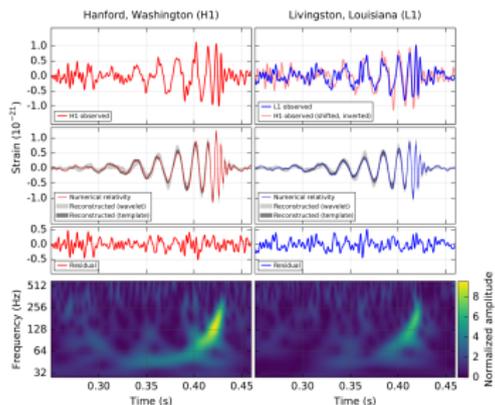


Stochastic gravitational waves

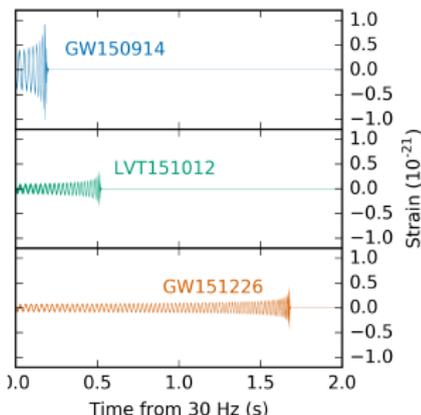


- sources: cosmological (big bang) or "background" of BBHs
- weak, long-lasting, all directions, all frequencies, power-spectrum
- looking for correlated GW signals between detectors

CBC: Detection/Discovery



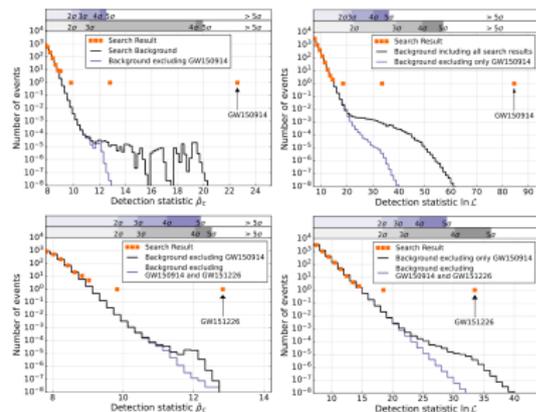
LVC, PRL116, 061102 (2016)



LVC, arXiv:1606.04856

Highly empirical/non-Bayesian:

- 2 detection pipelines (PyCBC, GstLAL)
- per-detector matched-filter SNR $\rho_{H1,L1}$
- “goodness-of-fit” re-weighting (e.g. χ^2) $\propto \hat{\rho}_{H1,L1}$
- keep coincident “triggers” ($\hat{\rho} > \text{threshold}$) within 15 ms
- combined ranking statistic $\hat{\rho}^2 = \hat{\rho}_{H1}^2 + \hat{\rho}_{L1}^2$
- What is the noise distribution / “background” ?
 \propto time-slides / interpolated detector trigger distribution
- p-value: $P(\hat{\rho} \geq \hat{\rho}_{\text{candidate}} | \text{background})$

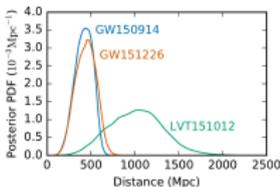
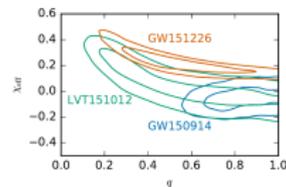
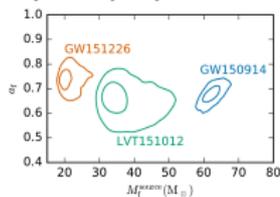
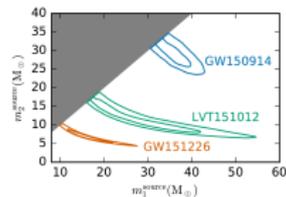


LVC, arXiv:1606.04856

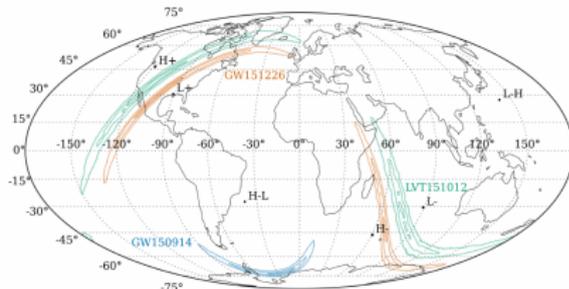
CBC: [fully Bayesian] Parameter estimation

- 15 parameters θ for full signal waveform:
 - 8 intrinsic: masses, spins
 - 7 extrinsic: sky-position, distance, orientation, time and phase
- ☞ Compute $P(\theta|\mathcal{H}_S, \mathbf{x})$: using stochastic samplers
 - Markov Chain Monte Carlo (MCMC)
 - Nested sampling
- Two families of “physical” waveforms (tuned against NR)
- marginize over calibration uncertainties

- ☞ real showcase application of Bayesian methods!
- ☞ Gravitational-wave “astronomy” is fully Bayesian!



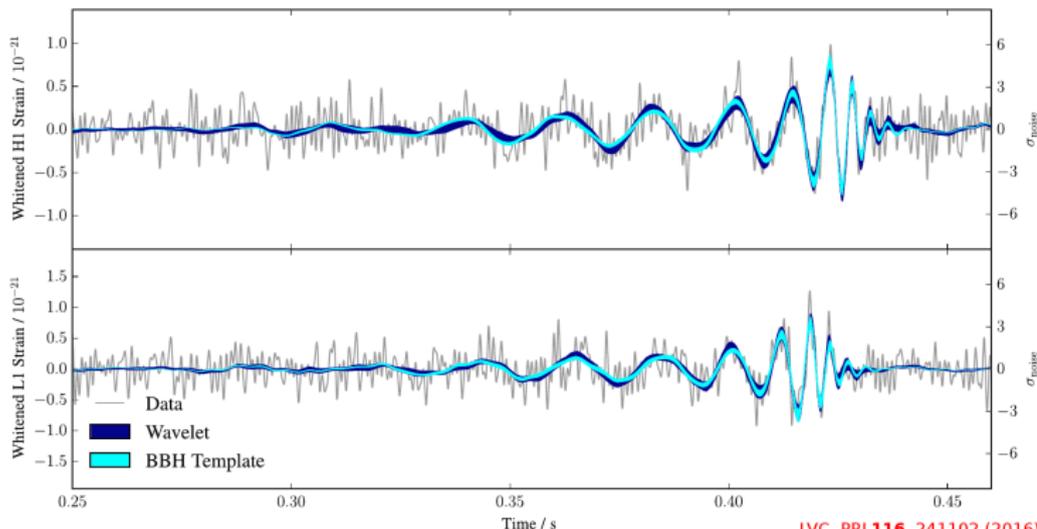
LVC, arXiv:1606.04856



LVC, arXiv:1606.04856

'Unmodelled' reconstruction

- relax assumption about inspiral waveform
- superposition of arbitrary number of sine-Gaussians “wavelets”
- Bayesian ('BayesWave') reconstruction of waveform
- agrees very well ($\sim 94\%$) with best-matching CBC waveform



LVC, PRL**116**, 241102 (2016)

GW150914: QNM ringdown

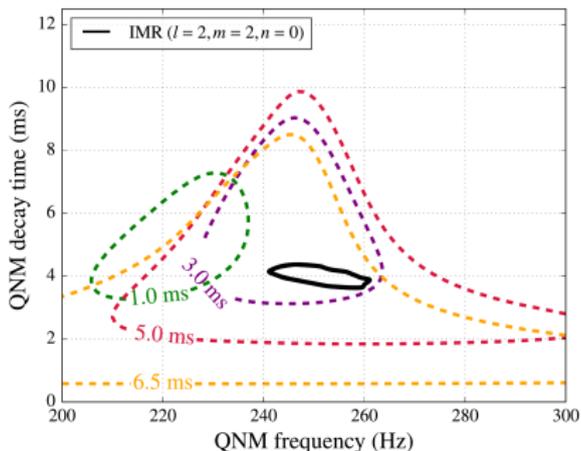
Surprise: GW150914 had a 'visible' ringdown post-merger!

- Bayesian parameter-estimation and evidence for damped sinusoid starting at t_0 :

$$h(t) = \mathcal{A} e^{-\frac{t-t_0}{\tau}} \cos(2\pi f(t-t_0) + \phi_0)$$

analytically marginalize $\{\mathcal{A}, \phi_0\}$, search $\{f, \tau\}$ at fixed t_0

- GR/NR: QNM ringdown frequency f expected to be stabilized $\sim 10 - 20M \approx 3.5\text{ms} - 7\text{ms}$ after merger
- posterior estimates of ringdown frequency and damping time consistent with GR prediction
- need ≥ 2 ringdown modes to test Kerr/no-hair theorem

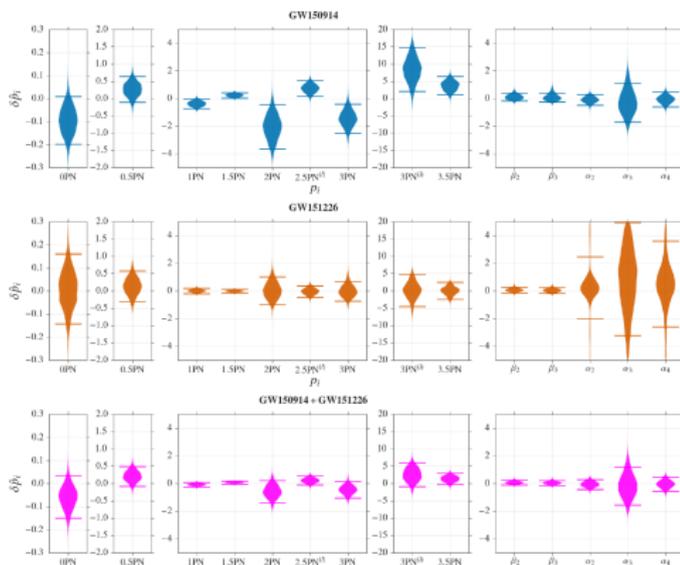


LVC, PRL**116**, 221101 (2016)

Tests of general relativity

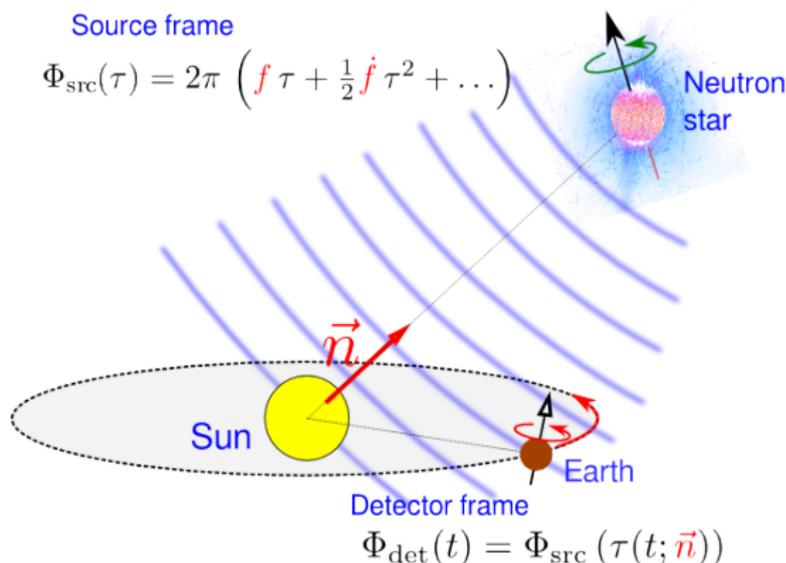
Express GR waveform in terms of post-Newtonian and phenomenological (merger+ringdown) coefficients. Test non-zero deviations from GR as “alternative hypothesis”, estimate relative deviations:

Waveform regime	Parameter	f dependence
Early-inspiral regime	$\delta\hat{\varphi}_0$	$f^{-5/3}$
	$\delta\hat{\varphi}_1$	$f^{-4/3}$
	$\delta\hat{\varphi}_2$	f^{-1}
	$\delta\hat{\varphi}_3$	$f^{-2/3}$
	$\delta\hat{\varphi}_4$	$f^{-1/3}$
	$\delta\hat{\varphi}_{5l}$	$\log(f)$
	$\delta\hat{\varphi}_6$	$f^{1/3}$
	$\delta\hat{\varphi}_{6l}$	$f^{1/3} \log(f)$
Intermediate regime	$\delta\hat{\beta}_2$	$\log f$
	$\delta\hat{\beta}_3$	f^{-3}
	Merger-ringdown regime	$\delta\hat{\alpha}_2$
$\delta\hat{\alpha}_3$		$f^{3/4}$
$\delta\hat{\alpha}_4$		$\tan^{-1}(af + b)$



LVC, arXiv:1606.04856

Continuous gravitational waves (CWs)

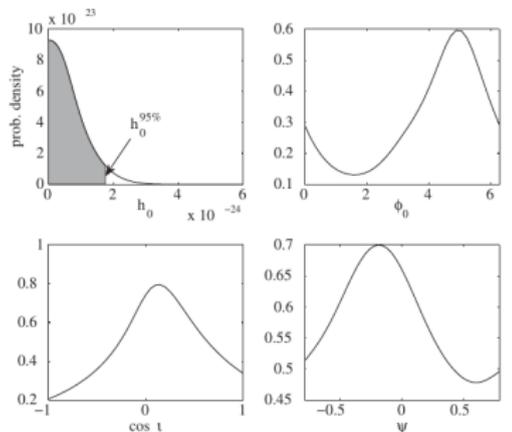


Measured signal strain $h(t; \mathcal{A}, \lambda)$ depends on

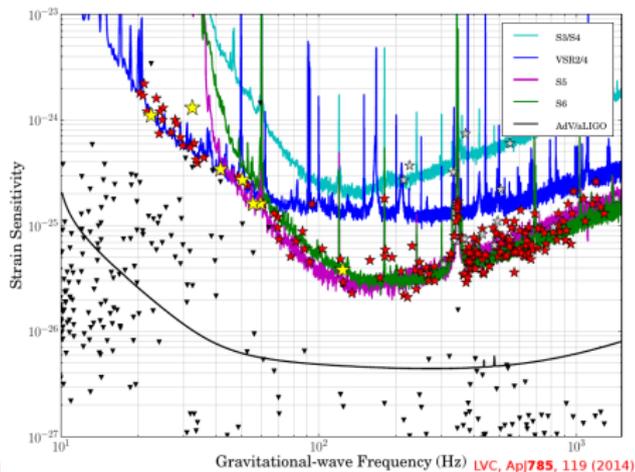
- **Amplitude** parameters: $\mathcal{A} \equiv \{h_0, \cos \iota, \psi, \phi_0\}$
- **Phase-evolution** parameters: $\lambda \equiv \{\vec{n}, f, \dot{f}, \dots\}$

Glasgow Bayesian known-pulsar ULs

- in use since first LIGO science run (S1) [2004]
- Bayesian parameter-estimation pipeline for amplitude parameters $\{h_0, \cos \iota, \psi, \phi_0\}$ for known λ (sky-position, frequency, spindown, ...) [Dupuis, Woan PRD72 (2005)]
- set 95% credible ULs on h_0 from posteriors
- most sensitivity search / ULs on known pulsars



LSC, PRD76, 042001 (2007)



Frequentist/orthodox approach: optimal statistic?

Simple hypotheses (\mathcal{A} known): Neyman-Pearson lemma

“Optimal”:= highest detection probability at fixed false-alarm

↳ Likelihood ratio is optimal: $\mathcal{L}(x; \mathcal{A}) \equiv \frac{P(x|\mathcal{H}_S, \mathcal{A})}{P(x|\mathcal{H}_G)}$

Unknown amplitude parameters \mathcal{A} ↔ \mathcal{F} -statistic

[Jaranowski, Królak, Schutz, PRD58 (1998)]

change \mathcal{A} -coordinates: $\mathcal{A}^\mu = \mathcal{A}^\mu(h_0, \cos \iota, \psi \phi_0)$

Likelihood ratio $\mathcal{L}(\mathbf{x}; \mathcal{A}) \propto \exp[-\frac{1}{2} \mathcal{A}^\mu \mathcal{M}_{\mu\nu} \mathcal{A}^\nu + \mathcal{A}^\mu x_\mu]$

↳ Can **analytically** maximize $\mathcal{L}(x; \mathcal{A})$ over \mathcal{A}^μ :

$$\mathcal{L}_{\text{ML}}(x) \equiv \max_{\{\mathcal{A}^\mu\}} \mathcal{L}(x; \mathcal{A}^\mu) = e^{\mathcal{F}(x)}$$

- widely-used CW statistics
- efficient (FFT) implementation, no explicit search over \mathcal{A}

Bayesian “re-discovery” of the \mathcal{F} -statistic

$$B_{S/G}(x) = \int \mathcal{L}(x; \mathcal{A}) \underbrace{P(\mathcal{A}|\mathcal{H}_S)}_{\mathcal{A}\text{-prior}} d^4 \mathcal{A}$$

simplest choice: *flat* \mathcal{A}^μ -prior: $P(\mathcal{A}^\mu|\mathcal{H}_S) = \text{const}$

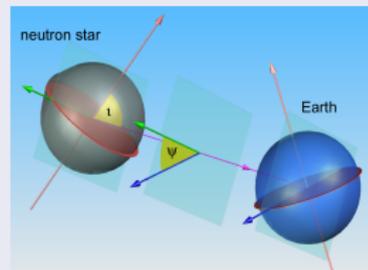
$$\implies B_{\mathcal{F}}(x) \propto \int \mathcal{L}(x; \mathcal{A}^\mu) d^4 \mathcal{A}^\mu \propto e^{\mathcal{F}(x)}$$

☞ ML \mathcal{F} -statistic is equivalent to Bayes factor with **flat \mathcal{A}^μ -prior!**

What is the “right” \mathcal{A} -prior?

Ignorance prior in physical coordinates $\{h_0, \cos \iota, \psi, \phi_0\}$:

- initial phase ☞ uniform in ϕ_0
- NS orientations equally likely isotropic ☞ uniform in $\{\cos \iota, \psi\}$
- h_0 : astrophysical prior or simplicity
 $\propto \{h_0^{-4}, h_0^{-1}, \text{const}\}$

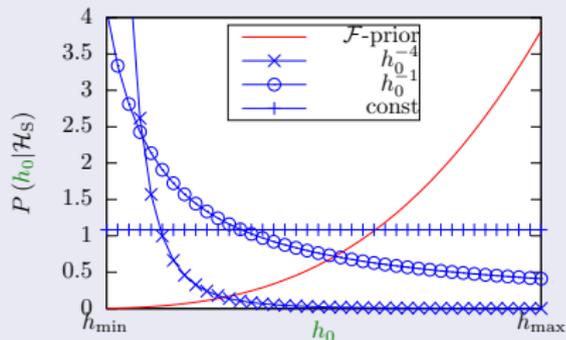
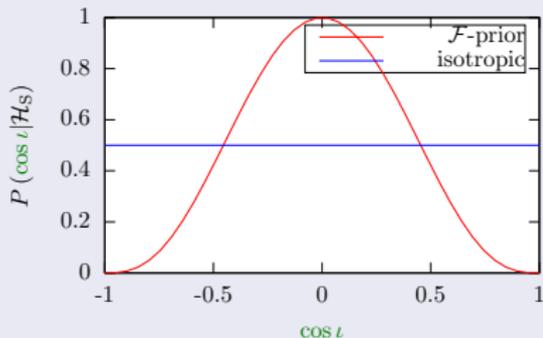


\mathcal{F} -statistic prior in physical coordinates:

$$P(\mathcal{A}|\mathcal{H}_S, \text{flat}\{\mathcal{A}^\mu\}) \propto \underbrace{h_0^3}_{\text{favors strong signals}} \times \underbrace{(1 - \cos \iota)^2}_{\text{favors linear polarization}}$$

“unphysical” in $\{h_0, \cos \iota\}$: ✗

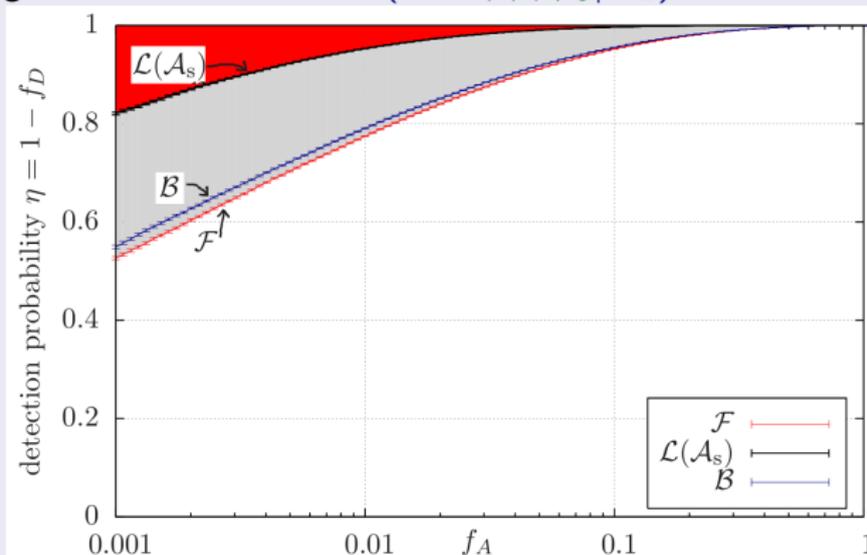
uniform in $\{\psi, \phi_0\}$: ✓



Bayes factor with “physical” \mathcal{A} -priors: “ \mathcal{B} -statistic”

$$B(x) \propto \int \mathcal{L}(x; \mathcal{A}) dh_0 d\cos\iota d\psi d\phi_0$$

Inject signals with uniform $P(\cos\iota, \psi, \phi_0 | \mathcal{H}_S)$ at fixed SNR=4



👉 \mathcal{F} -statistic is **not** N-P “optimal” [Prix, Krishnan, CQG26 (2009)]

👉 drawing from priors \implies Bayes-factor is N-P optimal!

[A. Searle, arXiv:0804.1161 (2008)]

Summary: \mathcal{F} -statistic versus Bayes factor

- classical maximum-likelihood \mathcal{F} -statistic can be interpreted as a Bayes factor, but with an *unphysical* implicit prior
[similar for burst searches: Searle, Sutton, Tinto CQG 26 (2009)]
- physical priors result in *optimal* Bayes factor $\mathcal{B}(x)$, but
 - gains in detection power rather minor
 - computing cost impractical (numerical \mathcal{A} -integration)
- \mathcal{F} -statistic is a **practical & efficient** \mathcal{B} approximation!
- Viewing $e^{\mathcal{F}}$ as a Bayes factor allows for better interpretation and extensions \Rightarrow line-robust statistics

Can we make \mathcal{F} more robust vs “line” artifacts?

Problem with $O_{S/G}(x) = P(\mathcal{H}_S|x) / P(\mathcal{H}_G|x) \propto e^{\mathcal{F}(x)}$

Anything that looks **more** like \mathcal{H}_S than Gaussian noise \mathcal{H}_G can result in large $O_{S/G}$, regardless of its “goodness-of-fit” to \mathcal{H}_S !
e.g. quasi-monochromatic+stationary detector artifacts (“lines”)

Alternative hypothesis \mathcal{H}_L to capture “lines”

“Zeroth order” simple line model:

$$\begin{aligned}\mathcal{H}_L &= \text{data } \mathbf{x} \text{ consistent with signal in only one detector} \\ &= \left[\left(\mathcal{H}_S^1 \text{ and } \mathcal{H}_G^2 \right) \text{ or } \left(\mathcal{H}_G^1 \text{ and } \mathcal{H}_S^2 \right) \right]\end{aligned}$$

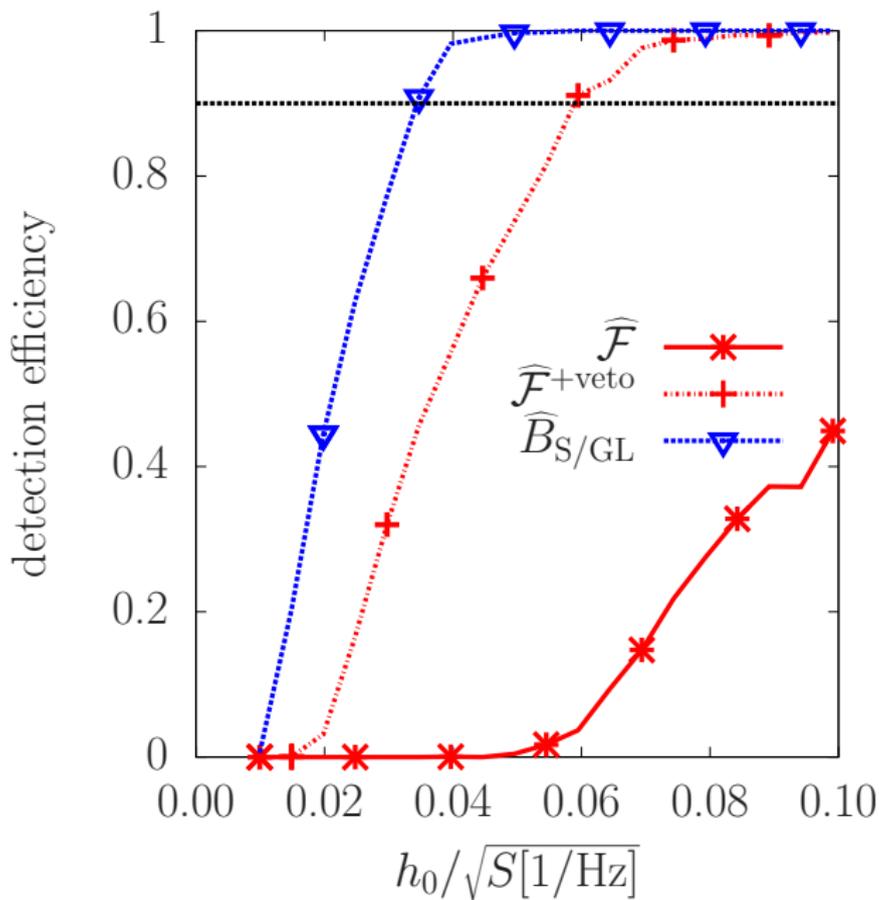
Extended odds: “line-robust” detection statistic

Use simple \mathcal{F} -statistic priors $P(\mathcal{A}^\mu | \mathcal{H}_L) = \text{const}$:

$$O_{S/GL}(\mathbf{x}) \equiv \frac{P(\mathcal{H}_S | \mathbf{x})}{P(\mathcal{H}_G \text{ or } \mathcal{H}_L | \mathbf{x})} \propto \frac{e^{\mathcal{F}(\mathbf{x})}}{e^{\mathcal{F}_*} + p_L^1 e^{\mathcal{F}^1(x^1)} + p_L^2 e^{\mathcal{F}^2(x^2)}}$$

[Keitel et al, PRD89 (2014)]

- recent “transient” extensions: [Keitel, PRD93 (2016)]
 - ➡ robust against transient lines (tL): $O_{S/GLtL}$
 - ➡ sensitive to transient signals (tS): $O_{tS/GLtL}$
- arbitrary prior cutoff h_{\max} leads to a “tuning parameter” \mathcal{F}_*
 - ➡ eliminate \mathcal{F}_* by using more physical prior approximation
e.g. $P(\mathcal{A}^\mu | \mathcal{H}_S) \propto e^{-\mathcal{A}^2/2\sigma}$ [work in progress]



Bayesian methods are gaining ground in GW searches ...

- ✗ Search/detection/"confidence" relies most heavily on empirical/frequentist methods
- ✓ Estimation of signal parameters and astrophysical rates ("GW astronomy") fully Bayesianized (CBC+CW)
- ✓ Various tests of General relativity
- ✓ Bayes factor with alternative hypotheses used in CW searches to be more robust versus detector artifacts ($O_{S/GL}$, $O_{S/GL\&L}$, $O_{tS/GL\&L}$)

👉 Help us find GWs and join Einstein@Home!

<https://einsteinathome.org>



Bayes-factor self-consistency relation

$$B_{S/G} \equiv \frac{P(x|\mathcal{H}_S)}{P(x|\mathcal{H}_G)} = \frac{P(B_{S/G}|\mathcal{H}_S)}{P(B_{S/G}|\mathcal{H}_G)}$$

👉 “Bayes factor predicts its own relative frequencies!”

[Prix, Giampanis, Messenger PRD84 (2011)]

